NC STATE UNIVERSITY



Mechanical and Aerospace Engineering



(MAE Undergrad / ABM

Knee Plug & Play Exoskeleton for **Knee Osteoarthritis**

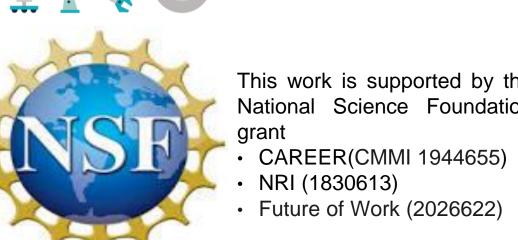
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Background and Opportunity

Knee Osteoarthritis (OA): A common condition causing pain, functional limitations, and reduced quality of life. Knee braces are explored as potential interventions to alleviate symptoms and improve joint function.

Overall Literature Review Findings:

- Soft knee braces reduce pain, improve walking performance, and enhance knee stability and confidence [1].
- Unloader braces reduce pain, improve functional outcomes, and increase joint space during gait [2].
- Knee braces are promising non-surgical interventions to alleviate pain and improve mobility in individuals with knee OA [3].

Existing Solution: University of Michigan Study [4] Comparison with Our System:

- Michigan's system uses custom-manufactured links, adding complexity, cost, and manufacturing time.
- Our system is designed to be plug-and-play: users can attach the actuator to any commercially available knee brace, eliminating the need for custom parts or specialized braces.
- Our goal: Offer a simpler, more cost-effective, and adaptable solution for users to integrate the technology into existing equipment.
- Their Exo: 2.8 kg vs. Our Exo: 1.5 kg (without battery/electronics)

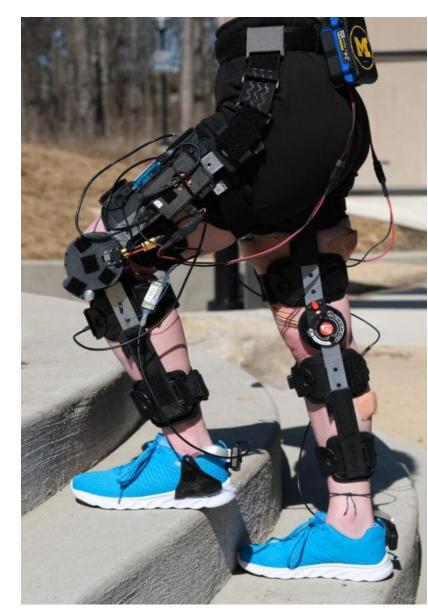




Figure 1: University of Michigan Knee Exo (left) vs. Our P&P Exo (right)

Design Specifications

The following details the preferred design specifications for our Knee Plug & Play Exoskeletal System:

Specifications	
Total Mass	< 3 kg
Form Factor	~ 50 mm
Brace Hinge	Single
Peak Torque	18 Nm
Battery Life	3 hours

The main goals of the design is to limit the weight (total mass) and provide a low profile that does not stick out far from the user's leg (form factor).

The Plug & Play System

Knee Exoskeleton:

- Exoskeleton designed to be attached to pre-existing soft brace solutions.
- Mounted mechanically to the knee brace and connected electrically to the PCB

Overall Design Considerations:

- Focus on functionality, accessibility, and ease of use.
- Designed to offer minimal bulk, intuitive controls, and a user-centric experience.



Figure 2: P&P Knee Exo Gait Cycle

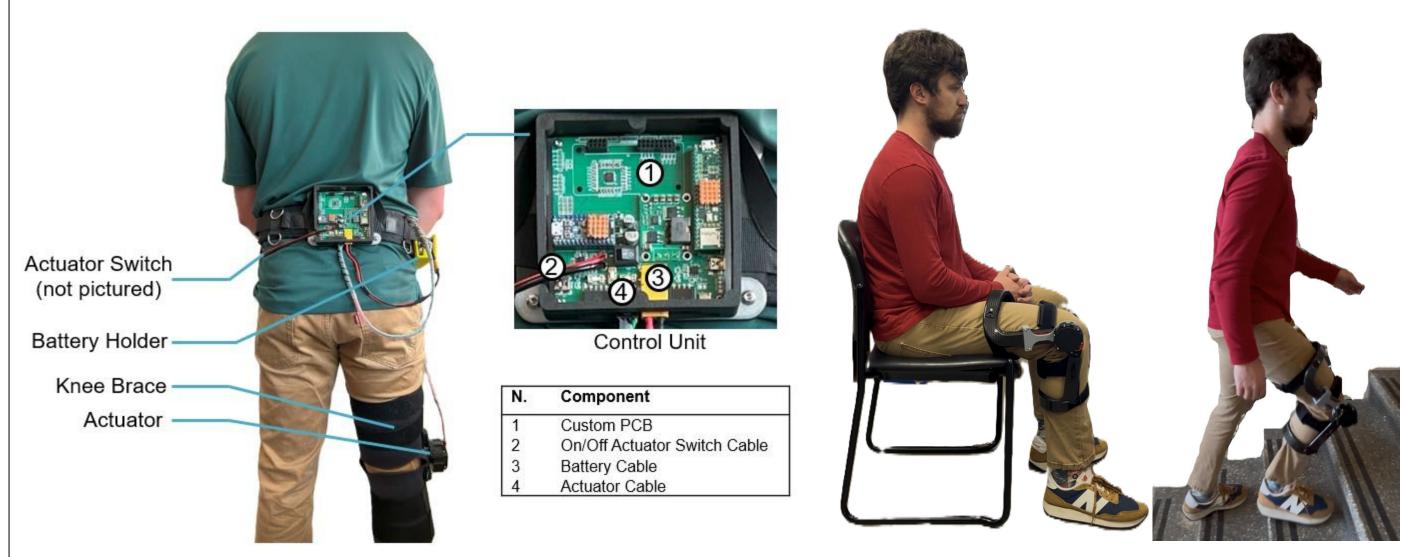


Figure 3: System Components

Figure 4: Sitting and Stair Climbing

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NeoG Adjusta Fit Hinged Open Knee Brace [5]

The NeoG knee brace was selected for our initial Plug & Play design. The goal of this design is to enable users to purchase an existing knee brace and easily attach our exoskeletal system to it, providing a seamless and accessible solution.

Features:

- Shank brace link is directly driven by the actuator.
- Actuator is mounted to the thigh brace link for natural force transmission.
- C-clamps secure the exoskeleton to existing braces from the underside.



Figure 6: NeoG P&P Actuator

Spring Loaded Knee Brace [6]

The Spring Loaded knee brace was selected for our second Plug & Play design. The current iteration is less of a plug-&-play model than the NeoG exoskeleton, but offers a direct-drive approach to the knee joint.

Features:



- Shank with a direct drive from the actuator.
- Assembly replaces the current plating and bearings at the joint.
- Actuator mounted directly to the brace at the joint.
- An additional c-clamp secures the assembly to the thigh link, can be hand tightened from the outside.

